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12. CHAPTER 1. P1.19. Introduction to Control Systems. A control system to keep a car at a given relative position offset from a lead car: Throttle. Position of follower

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and the Control System Toolbox or to LabVIEW and the MathScript RT Module. All of the computer solutions in this SolutionManualwere developed and tested on an Apple MacBook Pro platform using MATLAB 7.6 Release 2008a and the Control System Toolbox Version 8.1 and LabVIEW 2009. It is not possible to verify each solution on all the available ...

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First find the mechanical constants. $J_m = J_a + J_L (1.5 \times 10^{-4})^2 = 1 + 400(1.4 \times 10^{-4})^2 = 2$ $D_m = D_a + D_L (1.5 \times 10^{-4})^2 = 5 + 800(1.4 \times 10^{-4})^2 = 7$. 6 Solutions to Skill-Assessment Exercises. Now find the electrical constants. From the torque-speed equation, set $\omega_m = 0$ to find stall torque and set $T_m = 0$ to find no-load speed.

Solutions to Skill-Assessment Exercises

A variable resistor, called a potentiometer, is shown in Figure P1.1. The resistance is varied by moving a wiper arm along a fixed resistance. The resistance from A to C is fixed, but the resistance from B to C varies with the position of the wiper arm. If it takes 10 turns to move the wiper arm from A to C, draw a block diagram of the potentiometer showing the input variable, the output ...

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the Control System Toolbox or the LabVIEW and MathScript. All of the computer solutions in this Solution Manual were developed and tested on a Window XP platform using MATLAB 7.3 Release 2006b and the Control System Toolbox Version 7.1 and LabVIEW 8.2. It is not possible to verify each solution on all the available computer platforms that are compatible

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